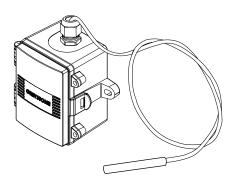
Modbus Flying Lead Temperature Sensor

Installation Instructions



INTRODUCTION

The single point flying lead temperature transmitter utilizes a precision sensor that is encapsulated in a 50 mm (2") long x 6 mm (0.236") diameter OD, 304 series stainless steel probe and is provided with 3.05 m (10') of plenum rated FT-6 cable. All probes provide excellent heat transfer, fast response and resistance to moisture penetration. A compact ABS enclosure with a hinged and gasketed cover is provided for ease of installation.

Features include a -40 to 100°C (-40 to 212°F) temperature measurement range, high accuracy and resolution, and auto-detect

baud rate. The network temperature sensor includes network variables for the temperature reading, °C/°F units and a calibration offset.

BEFORE INSTALLATION

Read these instructions carefully before installing and commissioning the temperature sensor. Failure to follow these instructions may result in product damage. Do not use in an explosive or hazardous environment, with combustible or flammable gases, as a safety or emergency stop device or in any other application where failure of the product could result in personal injury. **Follow electrostatic discharge precautions during installation and do not exceed the device ratings.**

MOUNTING

The flying lead sensor can be used in several different types of applications where single point temperature monitoring is required.

Listed below are some typical applications

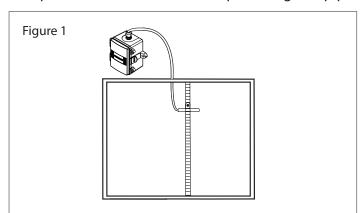
The flying lead sensor can be installed directly into any air duct. Select a suitable installation area in the middle of the duct. To achieve the best reading, do not place in an area where air stratification may be present. Avoid areas where the sensor is exposed to vibrations or rapid temperature changes.

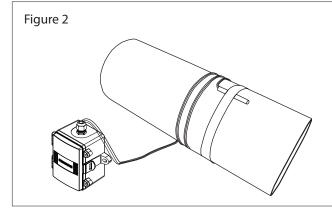
Once a suitable spot is selected, drill a 3/8" hole in the top of the duct and slide the probe through, mount a length of flexible duct hanger from top to bottom of the duct. Mount the probe to the duct hanger using a tube clamp or wire tie. See Figure 1.

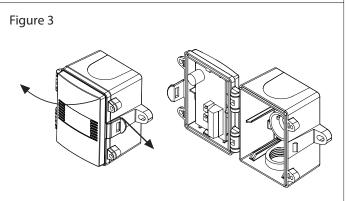
The flying lead could also be used to measure pipe temperature. Select a suitable spot along the pipe,

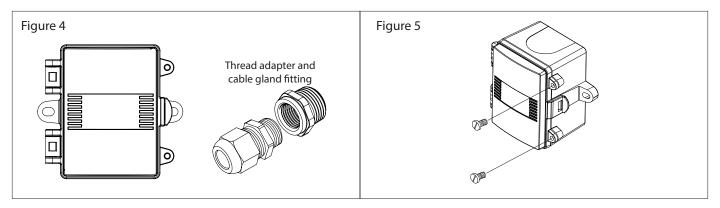
remove a small section of insulation if present and set aside. It is recommended that thermal compound be used to improve heat transfer. Spread a liberal amount on the pipe. Lay probe in thermal compound and secure sensor to pipe using a worm gear clamp (not included).

For added protection it is recommended to wrap the probe cable around the pipe 1 to 2 times. Reinstall insulation if present, allowing sensor cable to protrude. See Figure 2.









The enclosure has a hinged cover with a latch. Open the cover by pulling slightly on the latch on the right side of the enclosure. At the same time pulling on the cover, as shown in Figure 3.

A 1/2" NPT threaded connection hole is provided in the bottom of the enclosure. Screw the EMT connector or cable gland connector in until tight. See Figure 4. It is recommended that weatherproof conduit or cable gland fittings be used. The E style enclosure includes a 1/2" NPT to M16 thread adapter and cable gland fitting.

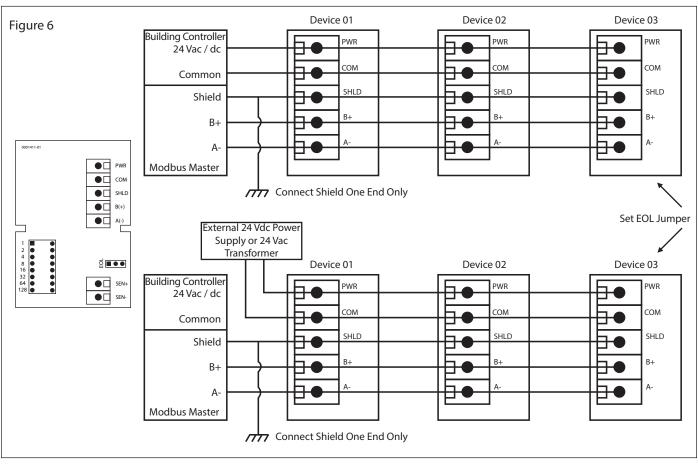
Make wiring connections as per the "Wiring" illustrations below.

Swing door closed until securely latched. For added security, 2 screws are provided that may be installed in the integrated screw tabs. See Figure 5.

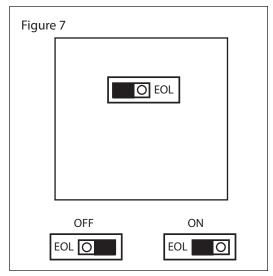
WIRING

Deactivate the 24 Vac/dc power supply until all connections are made to the device to prevent electrical shock or equipment damage. Use 14-22 AWG shielded wire for all connections and do not locate the device wires in the same conduit with wiring used to supply inductive loads such as motors. Pull at least six inches of wire into the enclosure and complete the wiring connections according to the wiring diagram. Make all connections in accordance with national and local codes.

Connect the plus DC or the AC voltage hot side to the PWR terminal and the power supply common is connected to the COM terminal. The device has a half-wave power supply so use caution when wiring multiple devices to that the circuit ground point is the same on all devices and the controller. Use caution if 24 Vac power is used and one side of the transformer is earth grounded. In general, the transformer should NOT be connected to earth ground when using devices with an RS-485 network connection. The device is reverse voltage protected and will not operate if connected backwards.



Connect the RS-485 network with twisted shield pair to the terminals marked A-, B+, and SHLD (shield) as shown in Figure 6. The positive wire connects to B+ and the negative wire connects to A- and the cable shield must be connected to the SHLD terminals of each device. If the device is connected to the end of the network, and end-of-line (EOL) termination resistor (121 Ω) should be installed in parallel with the A- and B+ terminals. This device includes a network termination jumper and will connect the resistor correctly on the PCB. Simply move the PCB jumper to the EOL position as shown in Figure 6 and no external resistor is required. The ground wire of the shielded pair should be connected to earth ground at the end of the network and the master is not grounded. Do not run bus wiring in the same conduit as line voltage wiring.



A network segment is a single shielded wire loop run between

several devices (nodes) is a daisy chain configuration. The total segment length should be less than 1220 metres (4000 feet) and the maximum number of nodes on one segment is 127. Nodes are any device connected to the loop and include controllers, repeaters and sensor such as the Network Temperature Sensor but does not include the EOL terminators. To install more devices, or to increase the network length, repeaters will be required for proper communication. The maximum daisy chain length (segment) depends on transmission speed (baud rate), wire size and number of nodes. If communication is slow or unreliable, it may be necessary to wire two daisy chains to the controller with a repeater for each segment.

LED OPERATION

In normal operating mode, the LED blinks for 30 second on setup at 1 Hz, then indicates communication activity. If the sensor reading is out of range then the LED stays on constantly to indicate a defect or over / under range condition.

NETWORK COMMUNICATION

The device parameters must be set before connection to the network and will ensure that each device has a uniques Modbus address. The PCB DIP switch is used to set the Modbus address (1-255) as shown in Figure 6.

Note that the Modbus network baud rate may be 9600, 19200, 38400, 57600, 76800, or 115200 and is auto-detected on start-up.

The sensor operates as a slave. It will not communicate unless a master is connected to the network and sends a request for information, then the slave will answer. If the device does not communicate properly, first check that the communication wires are not reversed. Then check that the slave address has a unique setting for the network segment it is connected to. Finally, verify that the device parity bit, stop bit, and RTU mode CRC polynomial are correct for the network it is connected to.

		D	IP Switc	h Positio	on					
128	64	32	16	8	4	2	1	Modbus Address	1	
OFF	OFF	OFF	OFF	OFF	OFF	OFF	ON	1	2	
OFF	OFF	OFF	OFF	OFF	OFF	ON	OFF	2	4 8	
OFF	OFF	OFF	OFF	OFF	OFF	ON	ON	3	16	
OFF	OFF	OFF	OFF	OFF	ON	OFF	OFF	4	32 64	
+	+	+	+	+	+	+	+	+	128	
ON	ON	ON	ON	ON	ON	ON	OFF	254	0.5	
ON	ON	ON	ON	ON	ON	ON	ON	255	OFI	= C

MODBUS PROTOCOL

This section describes the implementation of the Modbus protocol. It is intended to assist control system programmers who may need to add support to their systems to communicate with this device. The device communicates on standard Modbus networks using RTU mode transmission. It operates as a slave device (address from 1 to 255) and expects a Modbus master device to transmit queries, which it will answer.

RTU MESSAGE FORMAT

Modbus Framing	8 bit binary
Data Bits	start bits 1, data bits 8, parity bits none, stop bits 1
Baud Rate	9600, 19200, 38400, 57600, 76800, or 115200 (auto-detect)
Duplex	Half duplex
Error Checking	Cyclical Redundancy Check (CRC)
	CRC-16 Reversed polynomial x16+x15+x2+x0 (0xA001)
Latency	More than 3.5 characters minimum

RTU FRAMING SUPPORT AND BIT SEQUENCES

Start	1	2	3	4	5	6	7	8	Stop
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MODBUS REGISTER ADDRESSING

1000031	IEGIS I EIL	AUUI	123114G	<u> </u>				
Modbus Address	Typical Offset	Units	Data Type	Access	Notes			
40001	+0	°C/°F	Word	Read	16-bit integer, TEMPERATURE_VALUE x 10 Multiplier = 10 -400 to 1000 for -40.0 to 100.0°C, -400 to 2120 for -40.0 to 212.0°F			
40002	+1	°C/°F	Word	Read Write	16-bit integer, TEMPERATURE_OFFSET x 10			
40003	+2		Word	Read Write	16-bit integer, TEMPERATURE_UNITS 0 = °C, 1 = °F			

RTU FUNCTION CODES

0x03 --- Read holding registers

Query

Slave address	Function	Starting	Starting	Quantity of	Quantity of	CRC	CRC
(0x01 to 0xFF)	code (0x03)	address MSB	address LSB	Registers MSB	registers MSB	LSB	MSB

^{*}Starting address = 0x0000 to 0xFFFF, Quantity of registers = 0x0000 to 0x007D

Response

Slave address	Function	Byte count	Register	Register		CRC	CRC
(0x01 to 0xFF)	code (0x03)	2N	value MSB	value LSB	•••	LSB	MSB

^{*}N = Quantity of registers

0x06 --- Write single register

Query

Slave address	Function	Register	Register	Register	Register	CRC	CRC
(0x01 to 0xFF)	code 0x06	address MSB	address LSB	value MSB	value LSB	LSB	MSB

Response

Slave address	Function	Register	Register	Register	Register	CRC	CRC
(0x01 to 0xFF)	code 0x06	address MSB	address LSB	value MSB	value LSB	LSB	MSB

^{*}Register address = 0x0000 to 0xFFFF, Registers value = 0x0000 to 0xFFFF

Exception Response

Slave address	Function	Exception code	CRC	CRC
(0x01 to 0xFF)	code + 0x80	0x01, 0x02 or 0x03	LSB	MSB

^{*}An exception response is only returned if the CRC is correct Exception code 01 --- illegal function, 02 --- illegal address, 03 --- illegal data value

The RTU function codes supported are shown below.

Note that the registers may be read individually or all registers may be read at the same time as shown below.

To read all registers with one query...

0x03 --- Read ALL REGISTERS

Query

(0x01 to 0xFF)

Response

Slave address 0x03 0x06 Register MSB	value Register value CRC CRC LSB LSB MSI
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0x03 --- Read TEMPERATURE_VALUE

Query

Slave address (0x01 to 0xFF)	0x03	0x00	0x00	0x00	0x01	CRC LSB	CRC MSB
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Response

Slave address	0x03	0x02	Register value	Register value	CRC	CRC
(0x01 to 0xFF)	0x03	0x02	MSB	LSB	LSB	MSB

^{*}Register value = 0xFE70 to 0x03E8, corresponding to -40.0 to 100.0°C (multiplier - 10) or = 0xFE70 to 0x0848, corresponding to -40.0 to 212.0°F (multiplier - 10)

The temperature value is either in °C (default) or °F depending on the value of the TEMPERATURE_UNITS register.

This register has a multiplier of 10, the application must divide by 10 to obtain the correct value.

0x03 --- Read TEMPERATURE_OFFSET

Query

Slave address	0,402	0,400	0.01	0,,00	0.01	CRC	CRC
(0x01 to 0xFF)	0x03	0x00	0x01	0x00	0x01	LSB	MSB

Response

Slave address	1 0203	0x02		Register value		CRC
(0x01 to 0xFF)			MSB	LSB	LSB	MSB

^{*}Register value = 0xFFCE to 0x0032, corresponding to -5.0 to $5.0^{\circ}C$ (multiplier - 10) or = 0xFF9C to 0x0064, corresponding to -10.0 to $10.0^{\circ}F$ (multiplier - 10)

The temperature offset value is either in °C (default) or °F depending on the value of the TEMPERATURE_UNITS register.

This register has a multiplier of 10, the application must divide by 10 to obtain the correct value.

0x03 --- Read TEMPERATURE_UNITS

Query

Slave address	0.02	0,400	0,402	0,400	0,401	CRC	CRC
(0x01 to 0xFF)	0x03	0x00	0x02	0x00	0x01	LSB	MSB

Response

Slave address	0x03	0x02	Register value	Register value	CRC	CRC
(0x01 to 0xFF)	0x03	0x02	MSB	LSB	LSB	MSB

^{*}Register value = 0x0000 corresponding to °C = 0x0001 corresponding to °F

0x06 --- Write TEMPERATURE OFFSET

Query

Slave address	0x06	0x00	0x01	Register	Register	CRC	CRC
(0x01 to 0xFF)	UXUU	0.000	0.01	value MSB	value LSB	LSB	MSB

Response

Slave address (0x01 to 0xFF) 0x06 0x00 0	0x01	Register value MSB	Register value LSB	CRC LSB	CRC MSB
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^{*}The register is used to add or subtract an offset to the temperature value if necessary to confirm to a local reference.

Register value = 0xFFCE to 0x0032, corresponding to -5.0 to 5.0°C (multiplier = 10) = 0xFF9C to 0x0064, corresponding to -10.0 to 10.0°F (multiplier = 10)

The temperature offset value is either in °C (default) or °F depending on the value of the TEMPERATURE_UNITS register.

This register has a multiplier of 10, the application must divide by 10 to obtain the correct value. The operating temperature units (°C or °F) for the device should be selected first, and then add any offset if necessary.

0x06 --- Write TEMPERATURE_UNITS

Query

Slave address (0x01 to 0xFF)	0x06	0x00	0x02	0x00	Register value LSB	CRC LSB	CRC MSB	
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Response

Slave address	0x06	0x00	0x02	0x00	Register value	CRC	CRC
(0x01 to 0xFF)	UXUO	UXUU	UXUZ	000	LSB	LSB	MSB

^{*}Register value = 0x0000 = sets the device to °C operation = 0x0001 = sets the device to °F operation

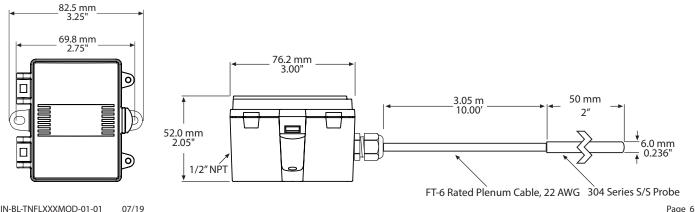
Exception response

Slave address	Function	Exception code *	CRC	CRC
(0x01 to 0xFF)	code + 0x80	0x01, 0x02 or 0x03	LSB	MSB

^{*}An exception response is only returned if the CRC is correct

Exception code 01 --- illegal function Exception code 02 --- illegal address Exception code 03 --- illegal data value

DIMENSIONS



IN-BL-TNFLXXXMOD-01-01

SPECIFICATIONS

GENERAL

Power Supply	24 Vac/dc ±20% (non-isolated half-wave rectified)
Consumption	10 mA max @ 24 Vdc
Protection Circuitry	Reverse voltage protected, transient protected

Operating Environment-40 to 50°C (-40 to 122°F), 10 to 95 %RH non-condensing

Wire Material FT-6 Plenum rated cable, 22 AWG

Wiring Connection......Screw terminal block (14 to 22 AWG)

Enclosure ABS, UL94-V0, IP65 (NEMA 4X)

Country of Origin......Canada

TEMPERATURE SENSOR

Sensor Accuracy..... ±0.2°C (±0.4°F)

Probe Sensing Range.....-20 to 60°C (-4 to 140°F)

Resolution......0.1°C/°F

MODBUS COMMUNICATION

Modbus Interface MS/TP (RTU), 2 wire RS-485

Address Range...... 1 to 255 (switch selectable)

Serial Configuration.....8N1

Error Checking......CRC-16 reverse (A001)

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